

# ARM Development Kit

## Cortex-M3

## STM32F103C8T6



# General Description

**Panda Kit** paves the way for beginners in discovering ARM processor-based embedded systems. It is based on the popular and cheap module Blue Pill which features 32-Bit ARM Cortex M3 microprocessor (STM32F103C8T6) running at 72MHz with 64KB of flash memory, 20KB of SRAM, and has an extensive range of I/O and peripherals.

## STM32F103C8T6 Features

Core : 32-Bit Cortex-M3

CPU frequency : 72MHz

Memory : 64KB flash , 20KB SRAM

GPIOs : 37

Timers : 3X16 bit

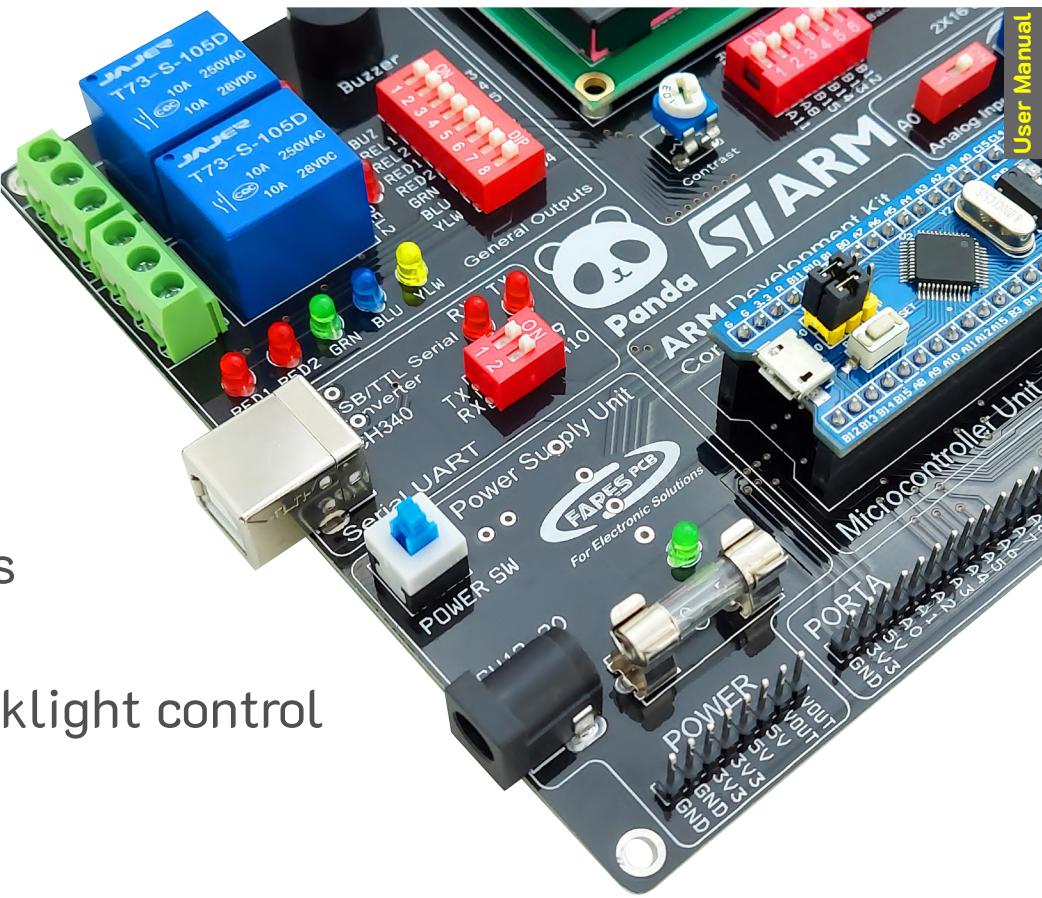
Analog : 10 (12-Bit)

Peripherals : 3XUSART , 2XSPI , 2XI<sup>2</sup>C , CAN 2.0 , USB 2.0 full speed

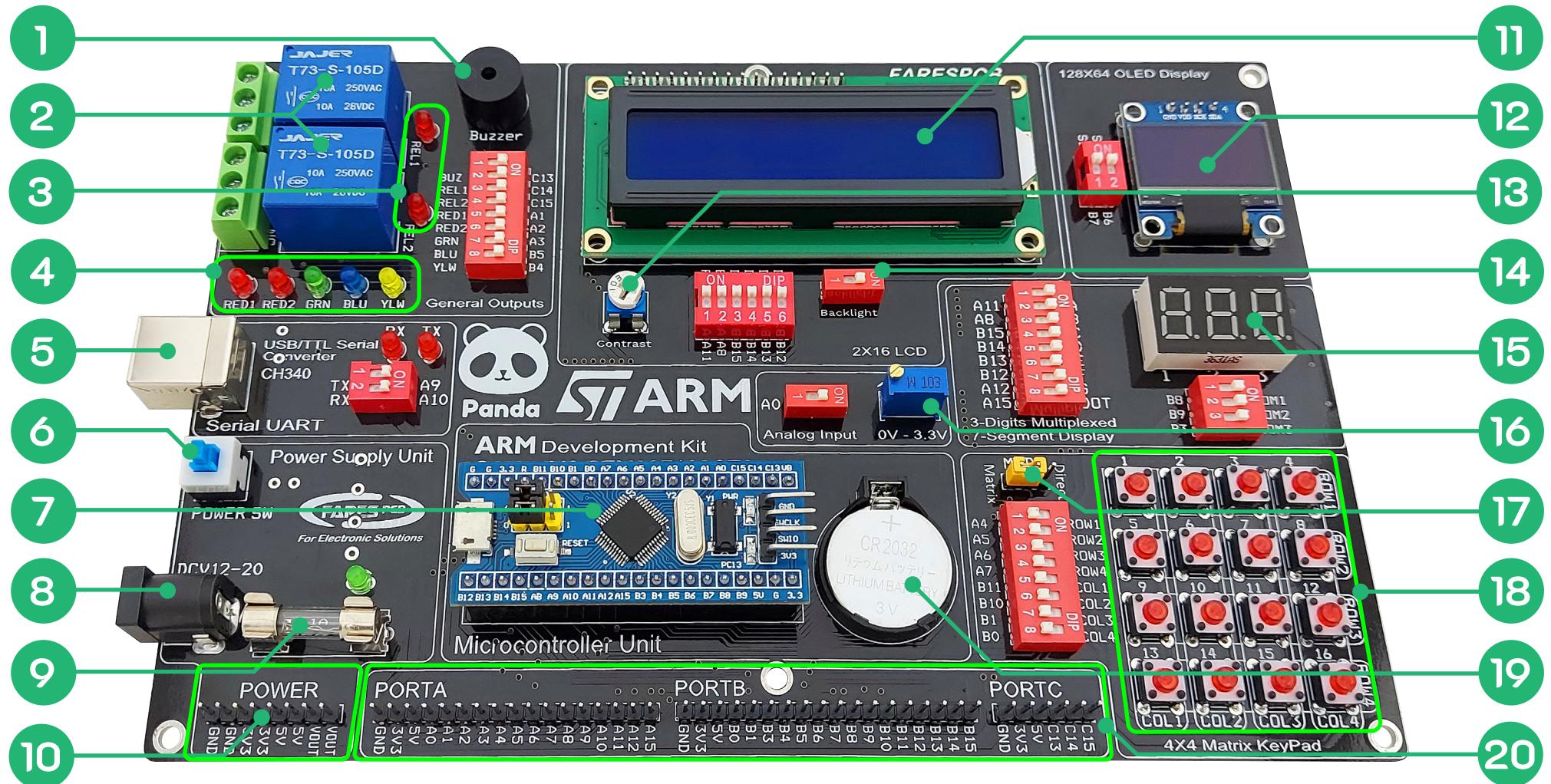
This manual explains kit sections and shows how it can be programmed in brief.

# Features

- Supports Cortex-M3 ( STM32F103C8T6 )
- USB or adaptor powered
- 16 Input switches with two operating modes
- Output unit involves
  - Five output LEDs
  - Two output relays with LED indicators
  - one output buzzer
- 2X16 Character LCD with contrast and backlight control
- 128X64 I<sup>2</sup>C OLED display
- Three digits 7segment display
- Analog input
- USB/TTL serial converter CH340
- All GPIOs are brought out to pin header



# Kit Sections



1 - 5V Buzzer

2 - 2X 10 Ampere relay

3 - LED indicator for relays

4 - Different color output LEDs

5 - USB type B interface

6 - Power switch

7 - Blue Pill module

8 - 2.1mm DC power socket

9 - 1A Fuse

10 - Power over header pins

11 - 2X16 LCD Display

12 - 128X64 OLED Display

13 - LCD contrast control

14 - Backlight control

15 - Three digits 7-segment display

16 - 10 KΩ multi-turn pot

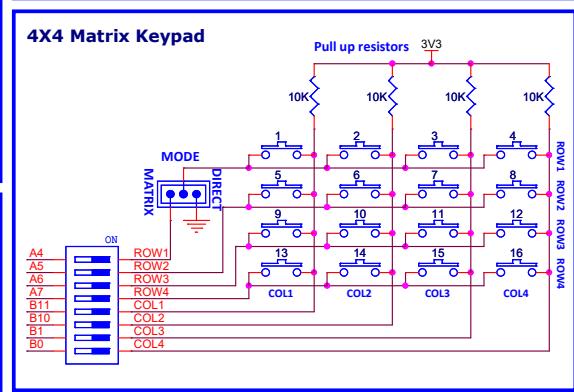
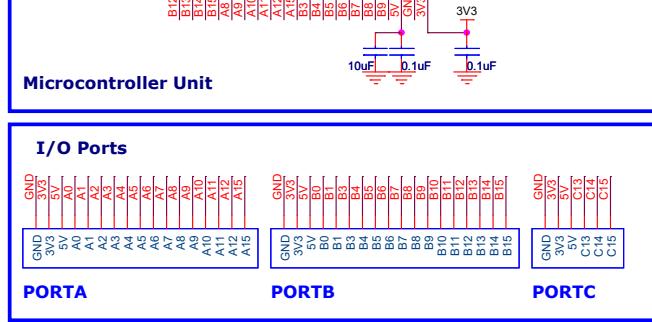
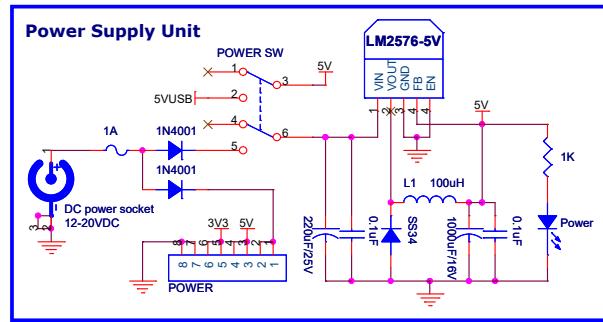
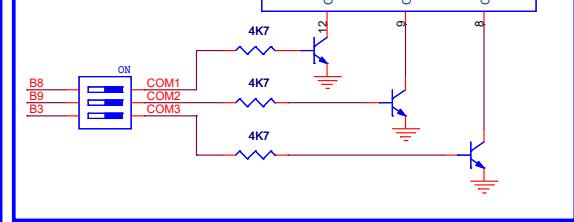
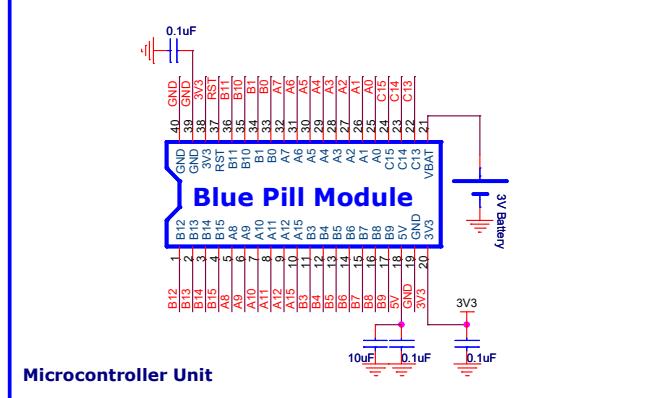
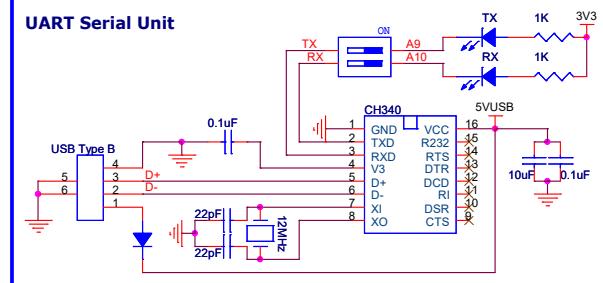
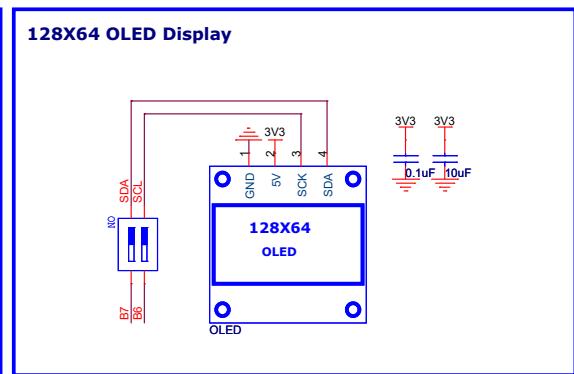
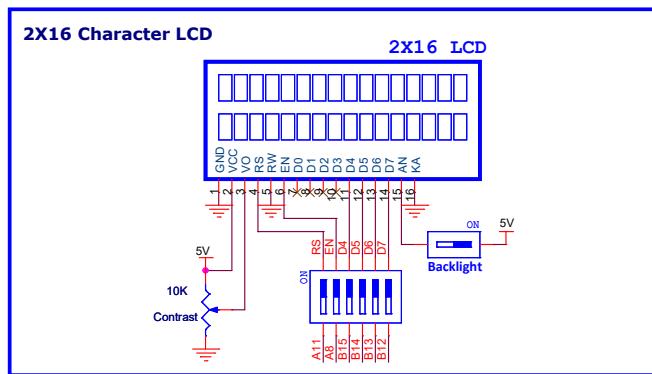
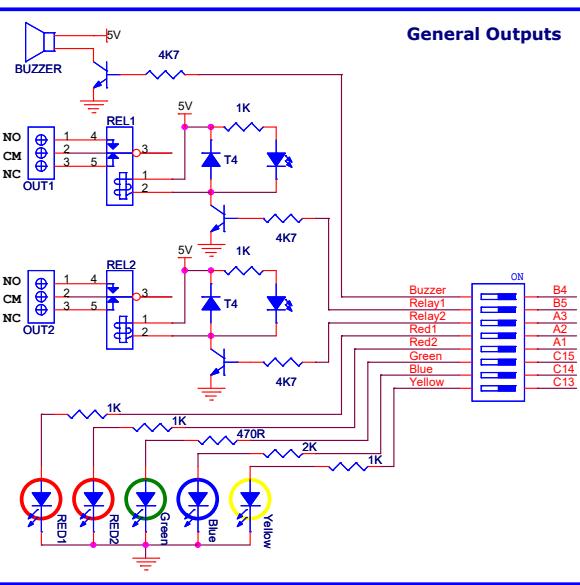
17 - Keypad mode select jumper

18 - 16 Switch keypad

19 - CR2032 lithium battery

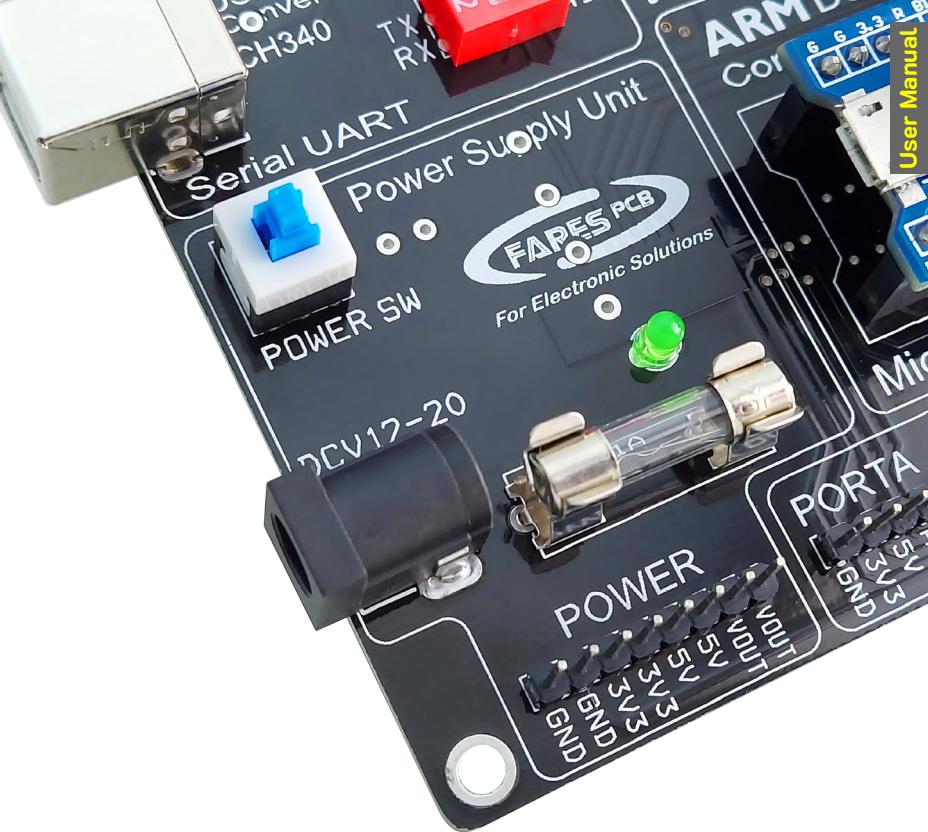
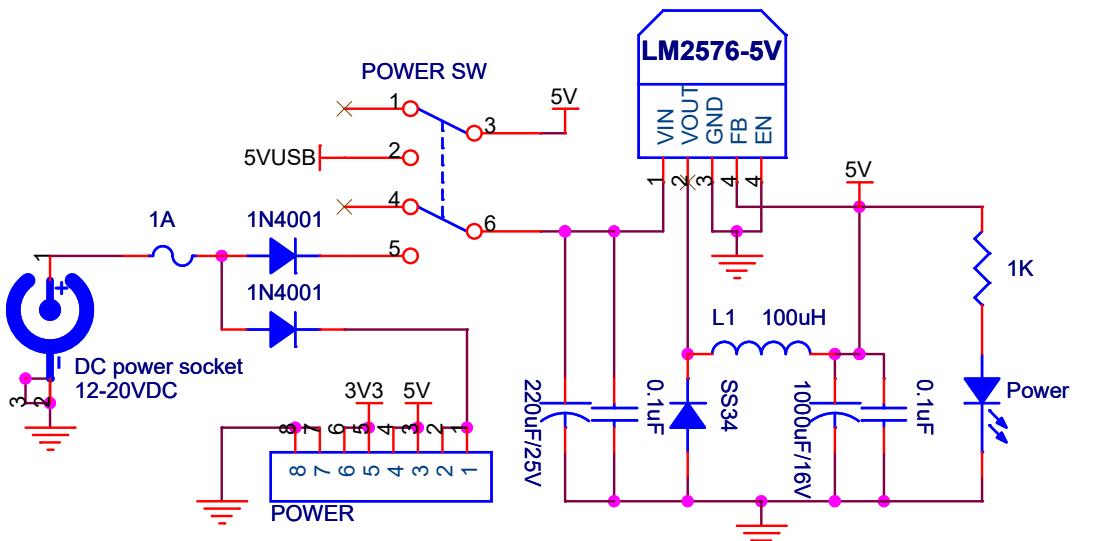
20 - GPIOs to pin header

# Schematic Diagram



# Power Supply Unit

Panda Kit can be powered from DC power supply adaptor (12-20V) via DC power socket or from power source over USB type B connector. Also, it can be powered directly from Blue Pill module via USB type B micro connector.



# PSU Specifications

- On/Off power switch
- Green LED for power indication
- 1A fuse for over-current protection
- On-board 5V switch regulator LM2576-5V
- Input voltage and on-board generated voltages are available for external usage via pin header
- On-board reverse current protection diode for safe operation

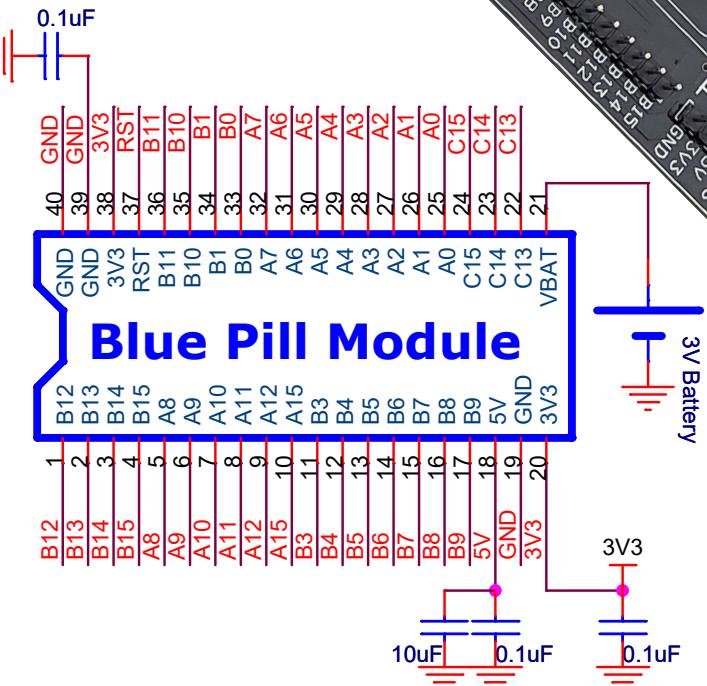
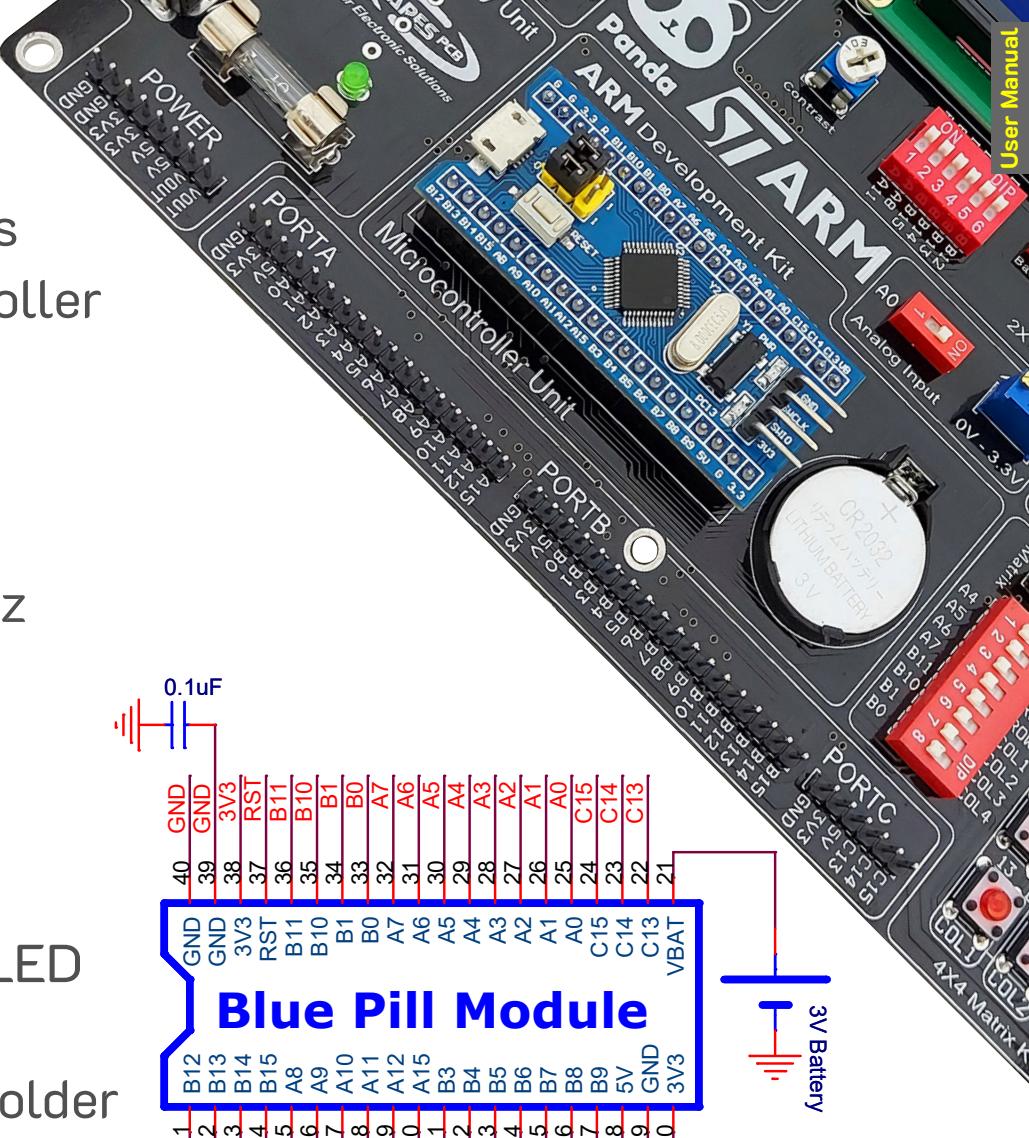
# Microcontroller Unit

Panda Kit supports Blue Pill module which is based on 32-bit ARM Cortex-M3 microcontroller STM32F103C8T6.

## Blue Pill Features

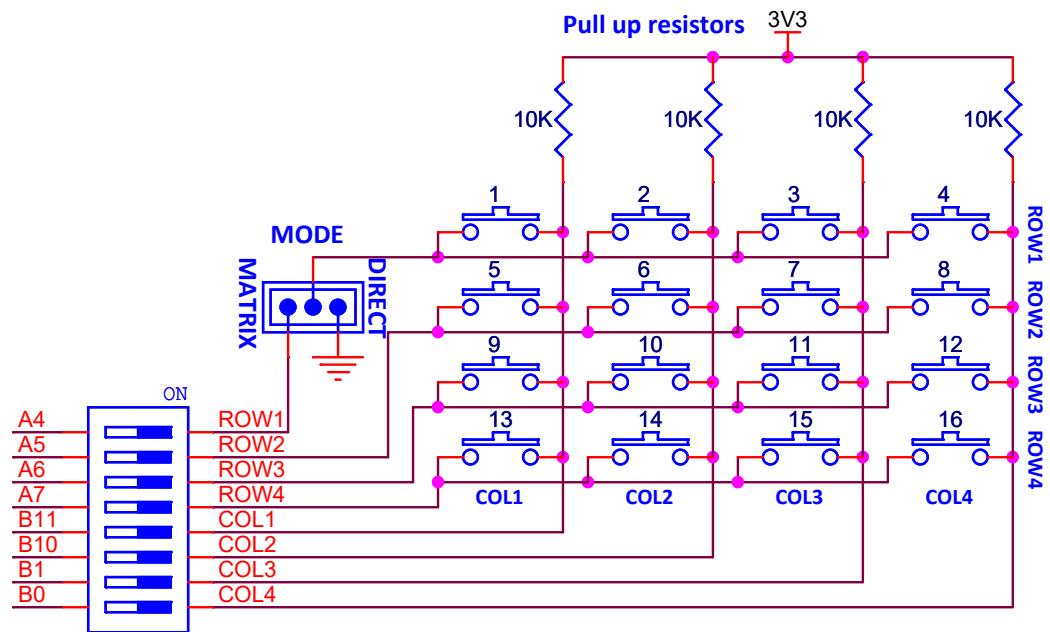
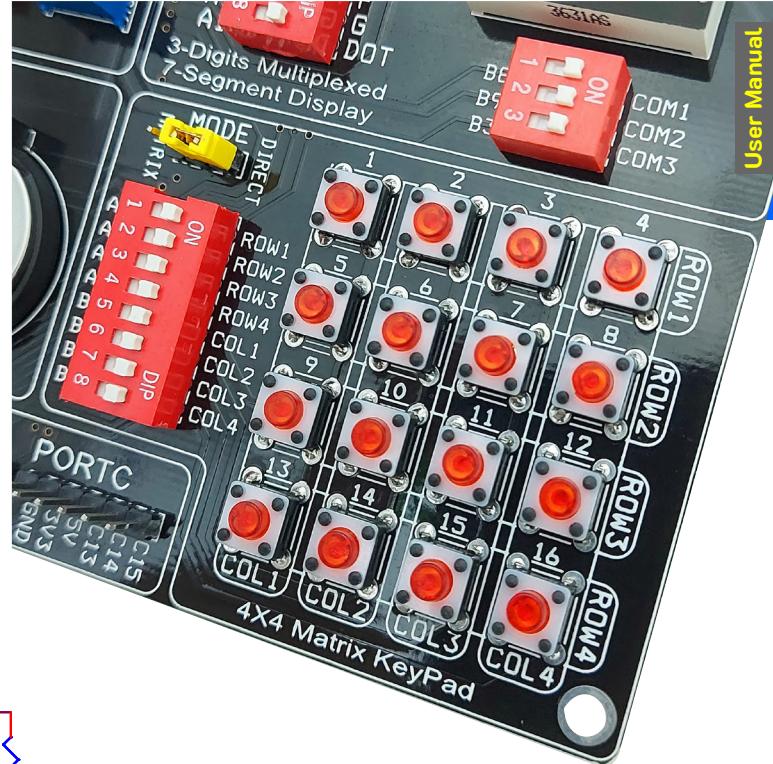
- STM32F103C8T8 ARM Cortex-M3 , 72MHz
- 64KB Flash memory, 20KB SRAM
- 32.768KHz crystal for RTC
- USB type B micro connector
- On-board 3.3V/300mA regulator
- On-board Reset switch and power indicator LED

A 3.3V lithium battery plugged on battery holder is included to power the internal RTC circuitry of microcontroller



# Keypad Unit

Panda Kit contains 16 push-button switches configured as four rows intersected by four columns. Each intersection creates a switch position. Microcontroller can scan switches using one of two modes (matrix mode or direct mode).



# Direct Mode

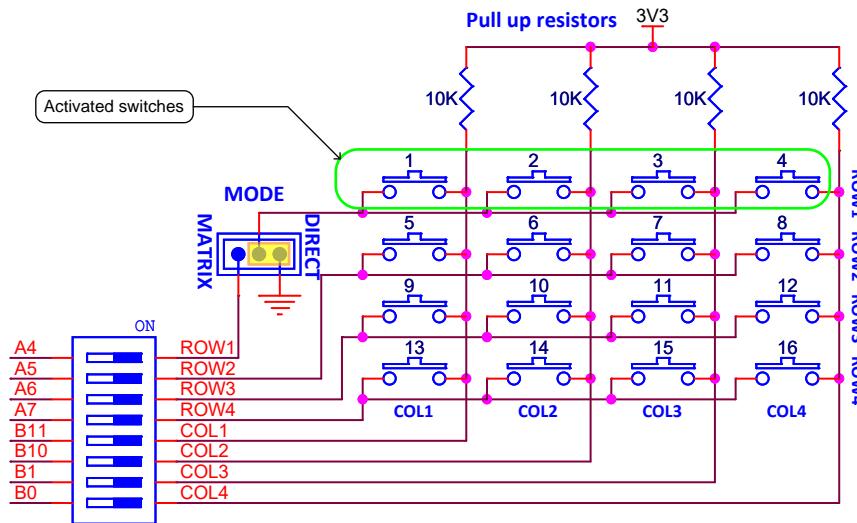
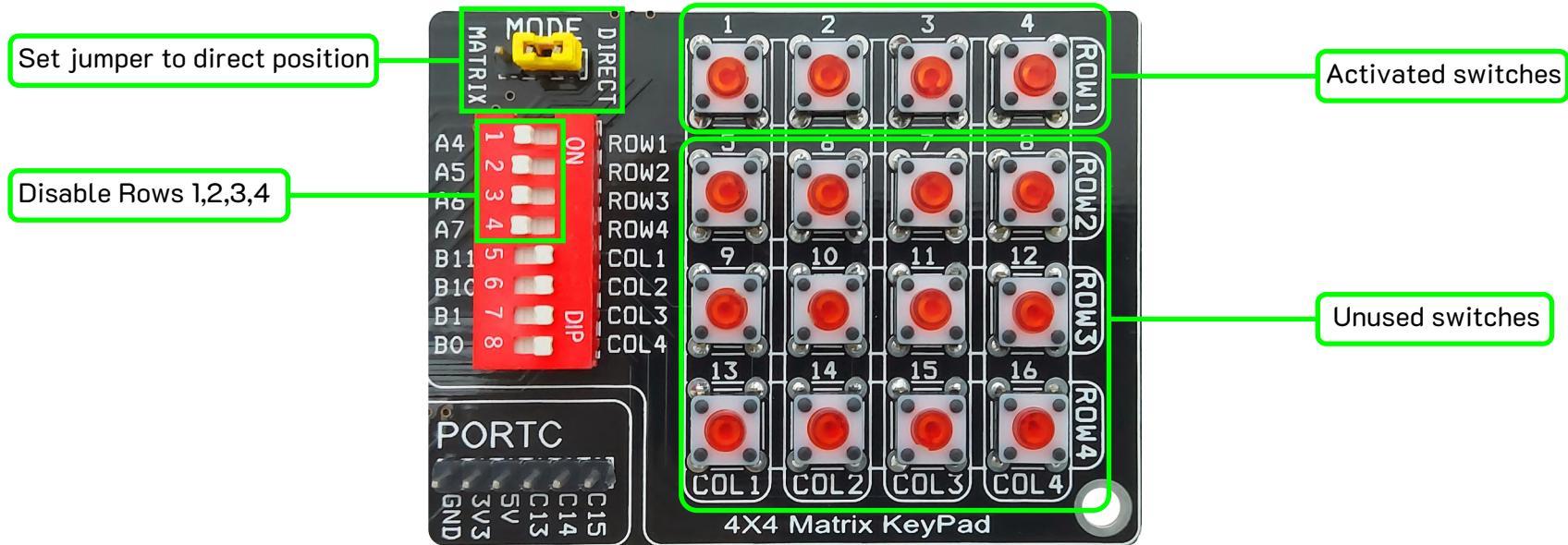
To configure keypad operation for direct mode, just set the MODE jumper to Direct position to assert a OV level on the first row thus enabling switches 1,2,3 and 4. so that, these switches can be read directly as inputs through column lines that are pulled up by  $10K\Omega$  resistors. If a column line goes low, it means a switch is pressed otherwise, it is considered released.

Direct mode configuration saves microcontroller I/O ports and reduces code size where no need for more than four switches.

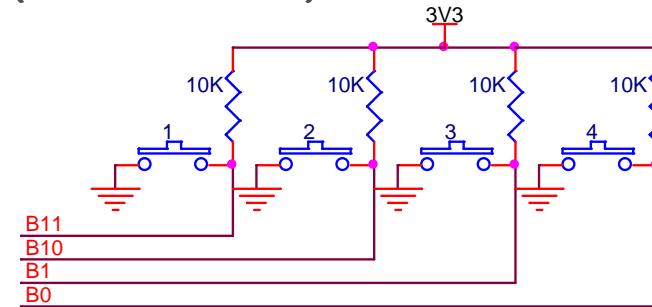
Activated switches are connected to microcontroller as shown in table below:

| Switch | MCU pins |
|--------|----------|
| SW1    | B11      |
| SW2    | B10      |
| SW3    | B1       |
| SW4    | B0       |

# Direct mode configuration



Simplified keypad circuit diagram  
(direct mode)



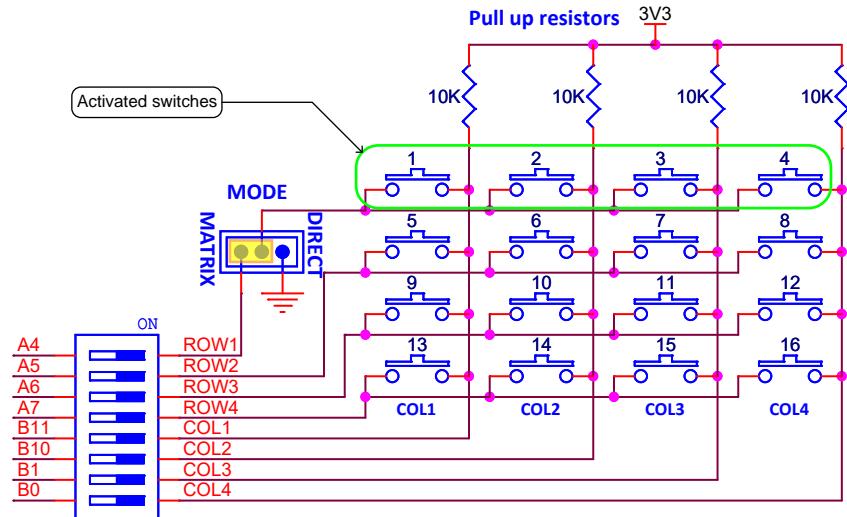
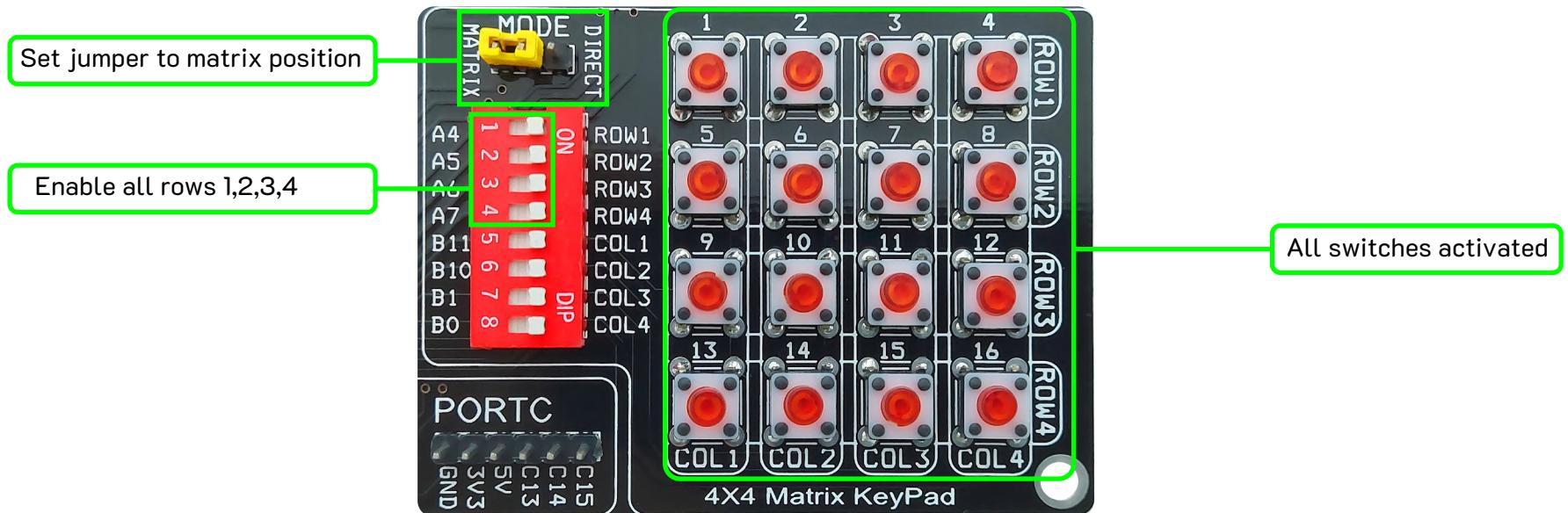
# Matrix Mode

All 16 switches are activated and configured as four row lines and four column lines. Microcontroller scans these lines to detect a pressed button. Column lines are pulled up by  $10K\Omega$  resistors. (i.e. microcontroller port pin reads high if no switch is pressed). Scan operation starts by setting all rows and columns as inputs. To scan switches in a row, microcontroller configures it as output and initiates it to low, then checks columns one at a time. If a column line goes low, microcontroller detects a pressed switch otherwise, no pressed switch is detected in this row hence, it goes to scan next row and, so on.

Rows and columns are connected to microcontroller as shown in table

| Switch | MCU pins |
|--------|----------|
| ROW1   | A4       |
| ROW2   | A5       |
| ROW3   | A6       |
| ROW2   | A7       |
| COL1   | B11      |
| COL2   | B10      |
| COL3   | B1       |
| COL4   | B0       |

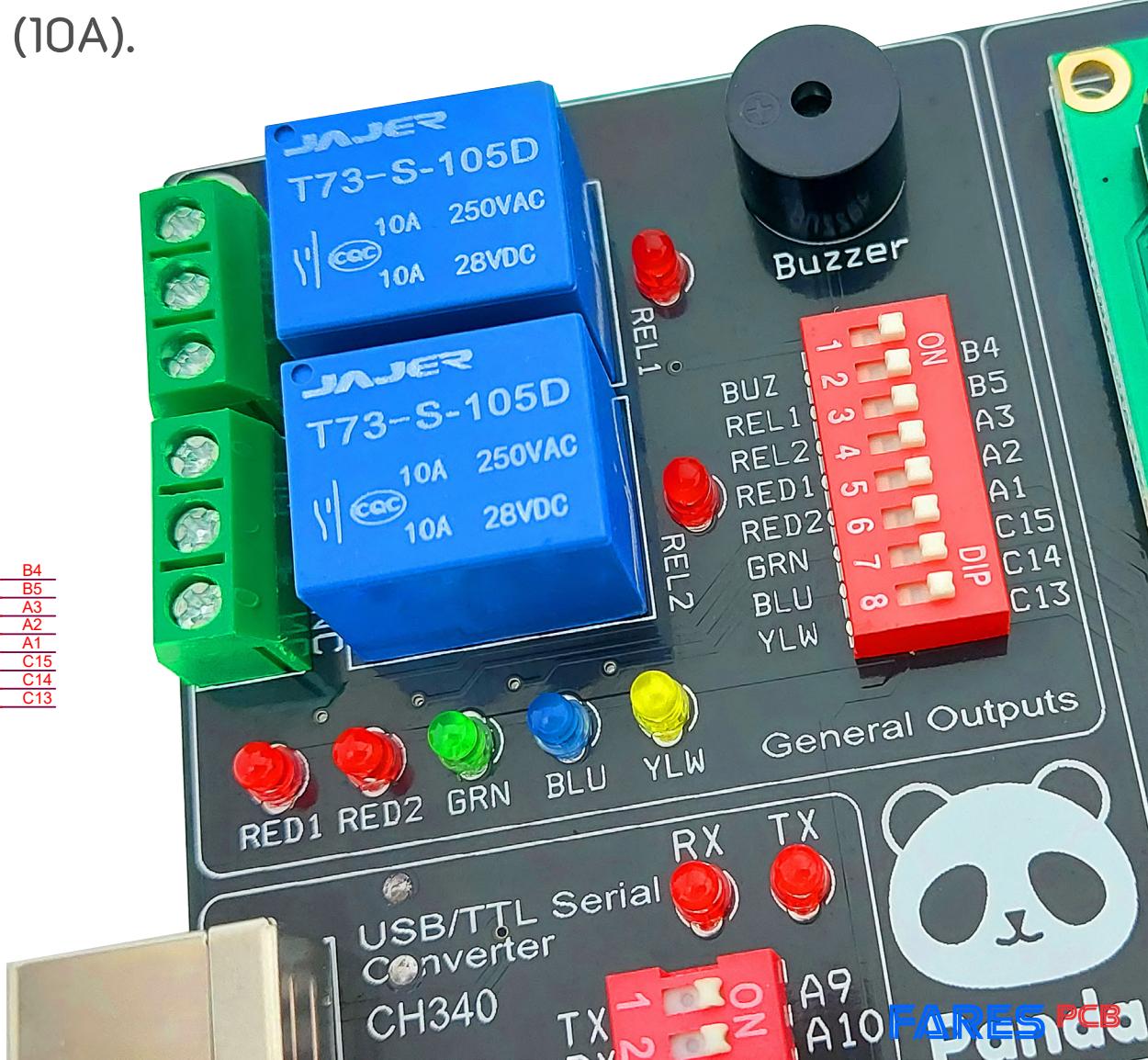
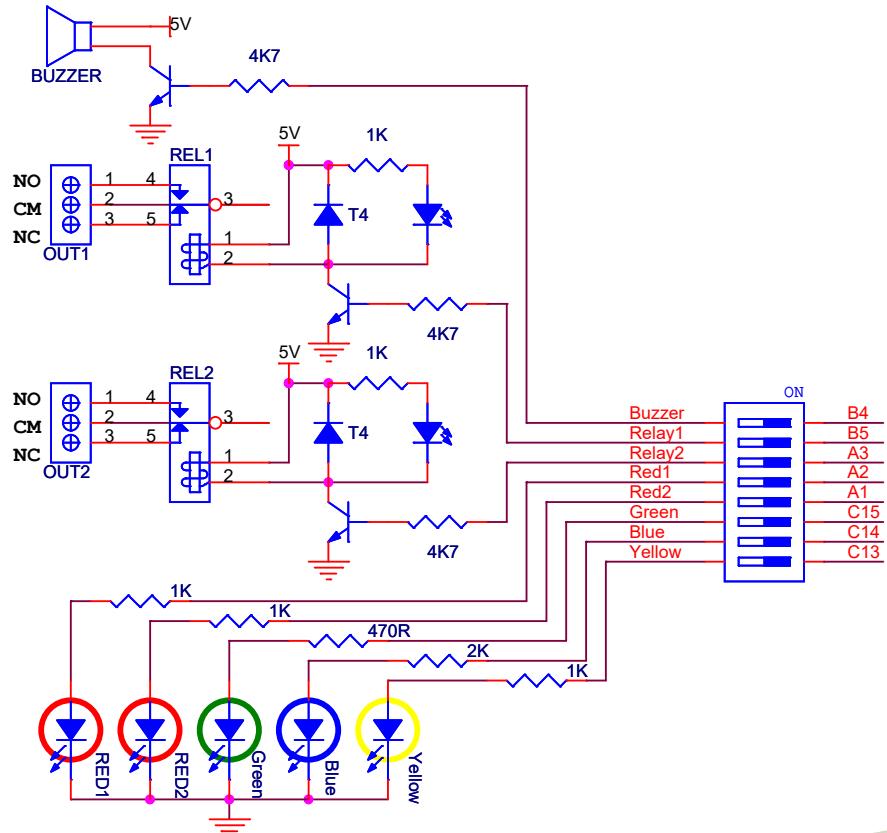
# Matrix mode configuration



# General Outputs

Panda kit provides a set of simple general outputs useful for beginners

- Five output LEDs Red1, Red2, Green, Blue, and Yellow.
- Two output relays REL1 and REL2 (10A).
- One output Buzzer (5V).



# Output LEDs

Five LEDs (Red1, Red2, Green, Blue and Yellow) with current limiting resistors are driven by  $\mu$ C pins A1, A2, A3, B5, and B4 respectively. LEDs are active high. i.e. output high turns LED on. Each LED can be individually enabled via DIP switch.

# Output Relays

Panda kit is equipped with two output relays, which are suitable for AC or DC switching applications. Each relay has its own LED status indicator and can be individually enabled via DIP switch. Relays are driven by NPN transistors. Freewheeling diodes are included to protect transistors from back EMF voltage that arises on relay coil during switching off. Relay1 and Relay2 are driven by  $\mu$ C pins C14 and C15 respectively. Relays are 5V coil and rated up to 10A contacts (resistive load). Both normally open and normally close contacts are brought out via screw terminals.

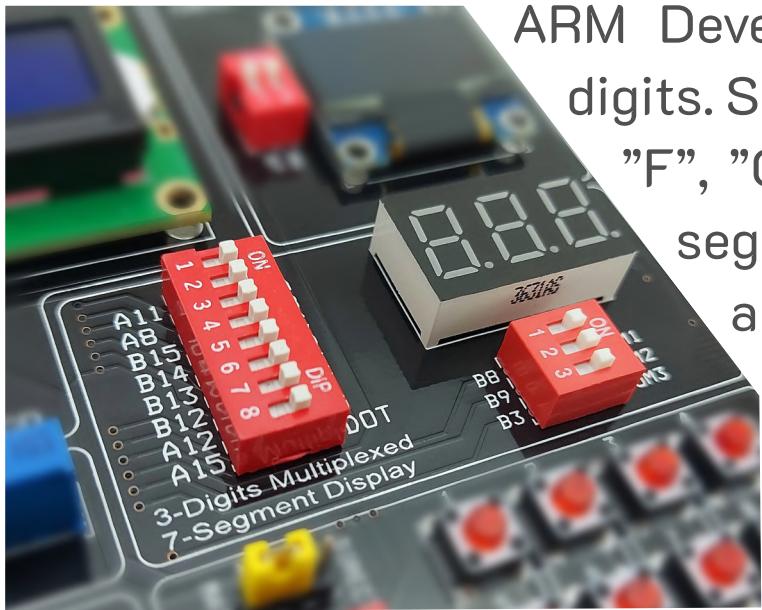
# Output Buzzer

One output buzzer (5VDC) is driven by an NPN transistor and connected to  $\mu$ C pin C13. Also, It can be enabled via DIP switch.

# 7-Segment Display

7-segment display is very popular and has many applications. It is used to indicate numerical data. It can display digits from 0 to 9 and some characters such as A, b, C, H, E, F ,etc.

ARM Development Kit provides three multiplexed 7-segment digits. Segments are referred to by letters "A", "B", "C", "D", "E", "F", "G", and "DOT". All digits share the same segment. i.e. segment "A" of DIG1, DIG2, and DIG3 are wired together and driven by the same  $\mu$ C pin. Each digit has its own common cathode which is driven by an NPN transistor. So, a high logic from microcontroller turns transistor on, which in turn enables the digit.



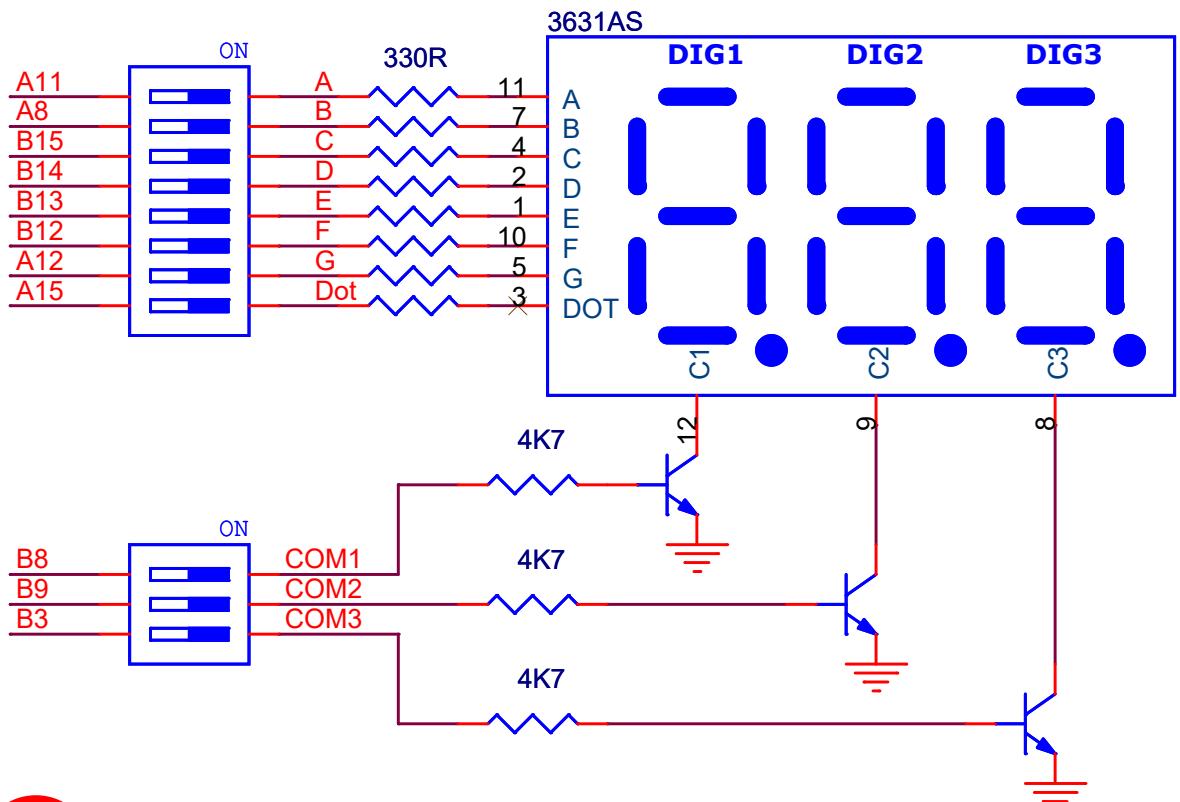
Each 7seg digit can be enabled or disabled individually using three way DIP switch.

Segments and commons are mapped to microcontroller as shown in tables below:

### 3-Digits Multiplexed 7-Segment Display

| Segment | MCU pins |
|---------|----------|
| A       | A11      |
| B       | A8       |
| C       | B15      |
| D       | B14      |
| E       | B13      |
| F       | B12      |
| G       | A12      |
| DOT     | A15      |

| Common | MCU pins |
|--------|----------|
| COM1   | B8       |
| COM2   | B9       |
| COM3   | B3       |



7segment and LCD modules share the same  $\mu$ C port. So, disable LCD before using 7Segment display.

# 2X16 LCD Display

LCD is a very popular electronic display module used in an extensive range of applications such as calculators and printers.

It is inexpensive, simply programmable, and has no limitations for displaying custom characters.

LCD Connector pinout is shown in table



- LCD R/W control is tied to ground.
- 10KΩ potentiometer denoted by "Contrast" is used to adjust the LCD contrast.

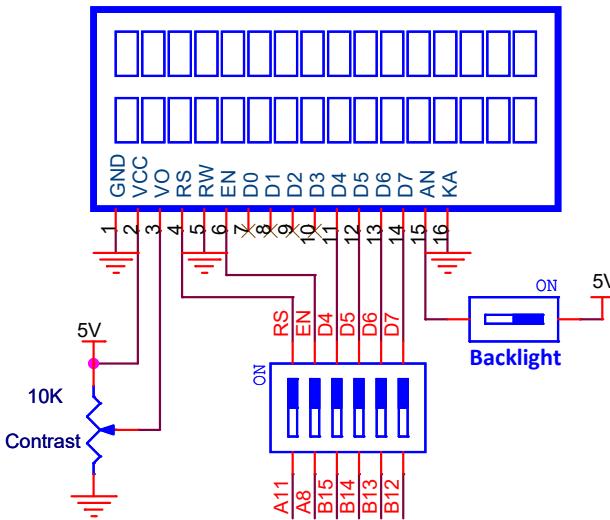
| LCD Pin No | LCD Pin Name | Function               |
|------------|--------------|------------------------|
| 1          | VSS          | Ground                 |
| 2          | VCC          | 5+V                    |
| 3          | VO           | Contrast               |
| 4          | RS           | Register Select        |
| 5          | R/W          | Read/Write             |
| 6          | EN           | Enable                 |
| 7          | DO           | Data bit 0             |
| 8          | D1           | Data bit 1             |
| 9          | D2           | Data bit 2             |
| 10         | D3           | Data bit 3             |
| 11         | D4           | Data bit 4             |
| 12         | D5           | Data bit 5             |
| 13         | D6           | Data bit 6             |
| 14         | D7           | Data bit 7             |
| 15         | A            | Back light anode (+)   |
| 16         | B            | Back light cathode (-) |

LCD is connected to microcontroller as shown in table below:

| LCD pin | MCU pins |
|---------|----------|
| RS      | A11      |
| EN      | A8       |
| D4      | B15      |
| D5      | B14      |
| D6      | B13      |
| D7      | B12      |



2x16 LCD



LCD and 7segment modules share the same µC port. So, disable 7segment display (turn off COM1, COM2, and COM3) before using LCD.

# OLED Display

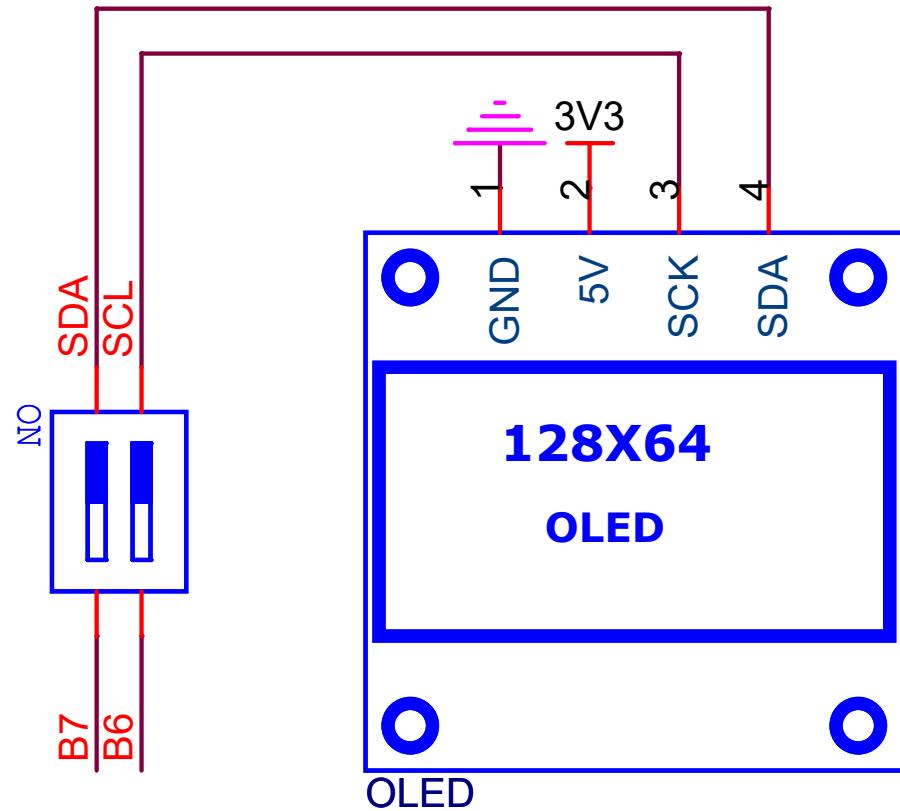
OLED display is more efficient than other displays. It doesn't require backlight, which results in a high contrast in the dark. Additionally, its pixels consume energy only when they are on, so the OLED display consumes less power.

**Panda** Kit provides 128X64 monochrome 0.96 inch OLED display (SSD1306). It has only four pins and communicates with microcontroller using I<sup>2</sup>C protocol. Operating voltage ranges from 3.3V to 5V.

I<sup>2</sup>C bus needs pull up resistors. Both on SDA and SCL lines. OLED display has its own 10K ohm internal pull-up resistors (Lines pulled up to 3.3V). So, There is no need for using external pull-up resistors.

OLED display is connected to microcontroller as shown in table below

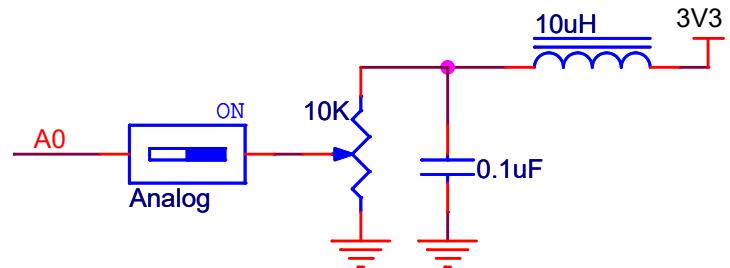
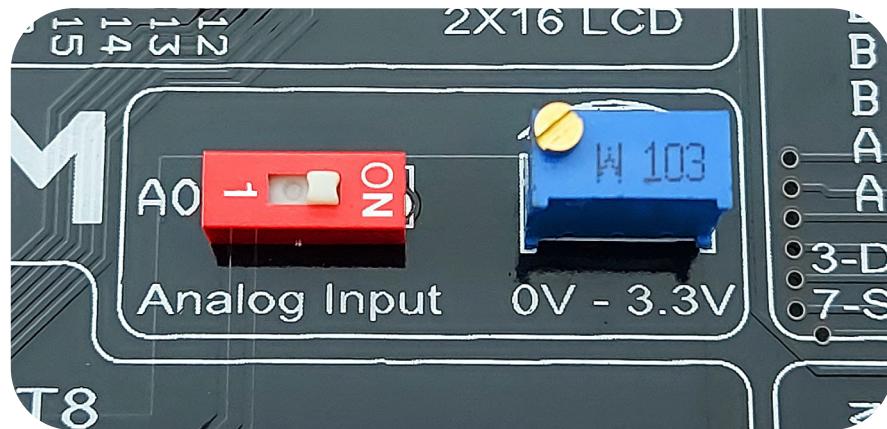
| OLED pin | MCU pins |
|----------|----------|
| SCL      | B6       |
| SDA      | B7       |



OLED Display module pull up the  $I^2C$  bus lines to 3.3V through internal 10K ohm resistors. If OLED is disconnected (DIP switch is turned off) then external pull-up resistors are required to use  $I^2C$  interface.

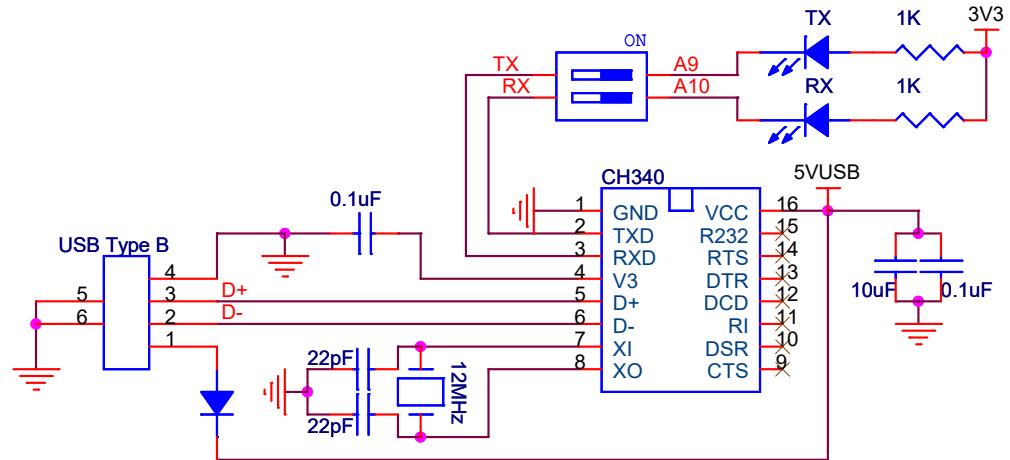
# Analog Input

Panda kit provides a variable analog input 0-3.3V through a 10Kohm multi-turn high precision potentiometer. Fixed terminals are connected to the power rails (GND and 3.3VDC) through an LC filter to eliminate power supply noise, and the variable terminal is routed to  $\mu$ C pin AO via DIP switch. The variable resistor can be precisely adjusted to a potential value in the range from 0.00V to 3.30V.



# USB Virtual Serial COM

Panda kit can be interfaced with the host computer over the USB-B connector. This unit contains USB to serial converter (CH340). CH340 is connected to RX, TX of the microcontroller internal UART peripheral through pins A10 and A9, which can be enabled individually via DIP switch. Two red LED included to indicate serial transmitting and receiving activity.



# I/O Ports

Panda kit offers interfacing with external devices and peripherals. All GPIOs available in Blue Pill module are brought out for external usage via headers. They are positioned at the lower side of the kit, so they can be easily accessed. The pins on these headers are labeled according to the names of the µC pins to which they are routed. Pin header connectors are grouped into three ports. Each represents one microcontroller port, in addition to power rails 5V, 3.3V, and GND to supply external circuits. Pin headers can be used to expand the connectivity of your **Panda** kit.



# Choose your Development Environment

Now after you get your **Panda** Kit, you own a hardware platform to be ready for taking your first step toward ARM-based embedded systems development world.

There are many development environments to work with STM32 MCUs such as STM32CubeIDE, Keil MDK-ARM, SEGGER Embedded Studio, and IAR Embedded Workbench. Of course, you can choose any of them according to your desire and preferences. But we recommend starting with STM32CubeIDE.

STM32CubeIDE is a free licensed complete development system to develop code for almost all STM-32 Based microcontrollers from ST Microelectronics. It's an advanced C/C++ development platform with great features that includes peripheral configuration, code editing, code compilation, and debugging.

you can download STM32CubeIDE from this link

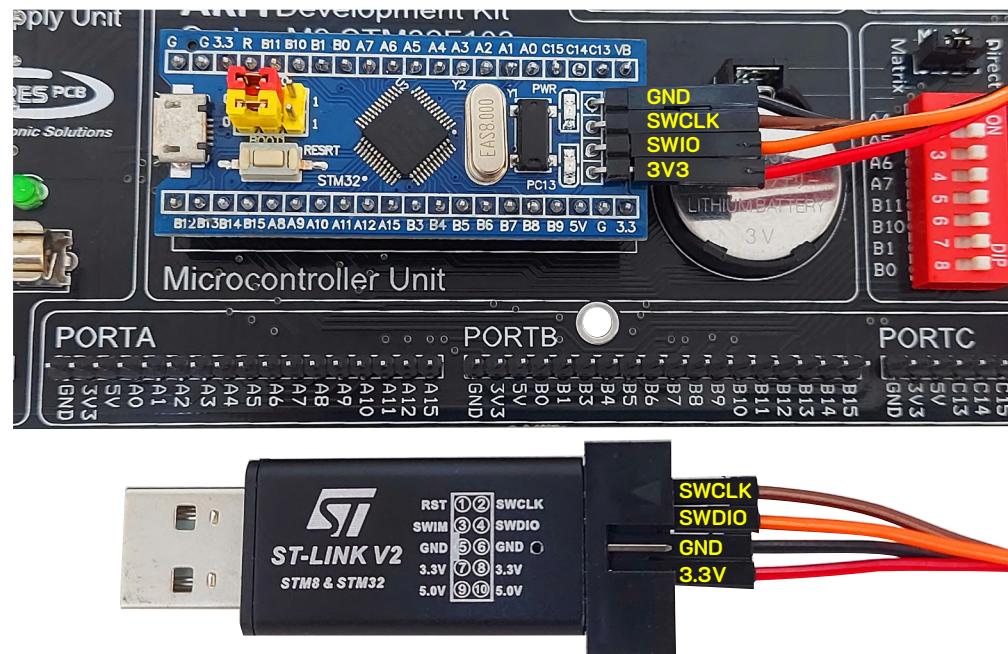
<https://www.st.com/en/development-tools/stm32cubeide.html>

# Debugging and Programming

After developing and building your project, you will need to upload it to MCU. Panda kit comes with ST-Link V2 . It is an in-circuit debugger and programmer for STM32 microcontrollers.

ST-LINK uses either single-wire interface module (SWIM) or JTAG/serial wire debugging(SWD) to communicate with microcontroller. Blue Pill module offers SW signals for debugging/programming. Connect the Blue Pill to ST-LINK as shown in picture and table

| Blue Pill | ST_LINK   |
|-----------|-----------|
| GND       | 6 (GND)   |
| SWCLK     | 2 (SWCLK) |
| SWIO      | 4 (SWDIO) |
| 3V3       | 8 (3.3V)  |



To upload your code, you can use STM32CubeProgrammer from STMicroelectronics. It provides an easy-to-use and efficient environment for reading, writing, and verifying device memory.

## STM32CubeProgrammer Features

- Erases, programs, views, and verifies the content of the device Flash memory
- Supports Motorola S19, Intel HEX, ELF, and binary formats
- Supports debug and bootloader interfaces
- Automates STM32 programming (erase, verify, programming, configuring option bytes)
- Supports the programming and configuring of option bytes
- Multi-OS support: Windows®, Linux®, macOS®

you can download STM32CubeProgrammer from this link

<https://www.st.com/en/development-tools/stm32cubeprog.html>

Once STM32CubeProgrammer is installed along with driver software, it is very easy to use



## Memory &amp; File editing



Device memory

Open file



Address 0x08000000

Size 0x400

Data width 32-bit

Find Data 0x

Read



| Address    | 0        | 4        | 8        | C        | ASCII                |
|------------|----------|----------|----------|----------|----------------------|
| 0x08000000 | 20005000 | 08003EC9 | 08003E59 | 08003E5F | .P. É>...Y>...>...   |
| 0x08000010 | 08003E65 | 08003E6B | 08003E71 | 00000000 | e>...k>...q>.....    |
| 0x08000020 | 00000000 | 00000000 | 00000000 | 08003E77 | .....w>...           |
| 0x08000030 | 08003E83 | 00000000 | 08003E8F | 08003E9B | .>.....>....>...     |
| 0x08000040 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x08000050 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x08000060 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x08000070 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x08000080 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x08000090 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x080000A0 | 08003F11 | 08003F11 | 08003F11 | 08003F11 | .?....?....?....?... |
| 0x080000B0 | 08003EA9 | 08003F11 | 08003F11 | 08003F11 | 0>...?....?....?...  |
| 0x080000C0 | 00000000 | 00000000 | 00000000 | 00000000 | .....                |

## Log

 Live Update   Verbose level
  1    2    3
 

```
13:58:16 : Address : 0x1ffff800
13:58:16 : Size : 16 Bytes
13:58:16 : UPLOADING ...
13:58:16 : Size : 1024 Bytes
13:58:16 : Address : 0x80000000
13:58:16 : Read progress:
13:58:16 : Data read successfully
13:58:16 : Time elapsed during the read operation is: 00:00:00.007
```



100%

ST-LINK

ST-LINK configuration

Serial number: 110029...

Port: SWD

Frequency (kHz): 4000

Mode: Normal

Access port: 0

Reset mode: Software reset

Speed: Reliable

Shared: Disabled

Debug in Low Power mode:

External loader

Target voltage: 3.23 V

Firmware version: V2J29S7

Target information

Board: STM32F101/F102/F103 Medi...

Device: STM32F101/F102/F103 Medi...

Type: MCU

Device ID: 0x410

Revision ID: Rev X

Flash size: 128 KB

CPU: Cortex-M3

Bootloader Version: --

# Tips before first use

If it is the first time to use kit or need to make sure of the validity of kit sections, It is a good decision to test all kit parts before uploading your own application.

**Panda** kit comes preprogrammed with a comprehensive test code for all kit sections.

If **Panda** kit is not programmed with the test code, you can download it from the below link

<https://fares-pcb.com/product/arm-development-kit-panda/>

Use the STM32CubeProgrammer to upload the test code to kit as previously described

Connect **Panda** kit to PC via USB type B socket and enable DIP switches of all sections on kit. Turn on the power switch located in PSU (denoted by POWER SW).

on powering on kit either from DC adaptor or USB socket, You can start testing immediately after the next messages are displayed successively on LCD

FARES PCB Co.

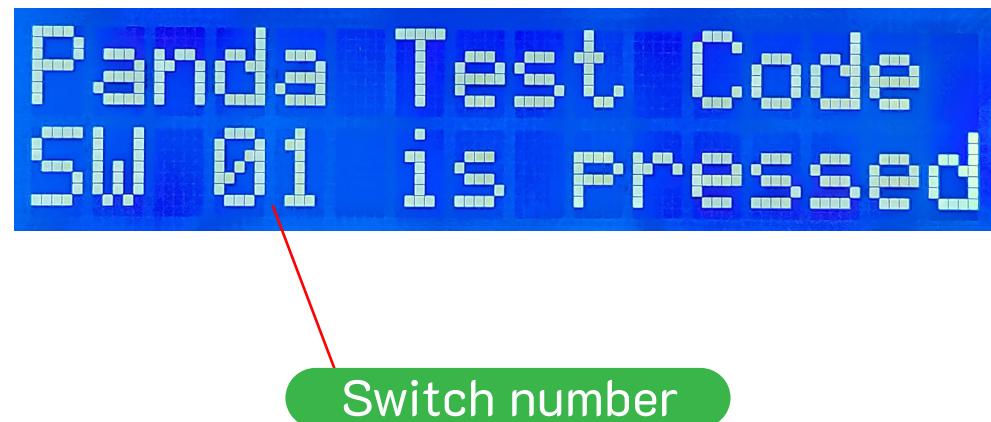
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ARM Development  
Kit STM32F103

Panda Test Code  
SW -- is Pressed

# Test Operation

Some switches perform a test operation for specified modules in kit. If a switch is pressed, the microcontroller sends a message to the serial port containing the pressed switch number and simultaneously LCD displays the same message as the below one



The next table shows the test operation of each switch and LCD message is displayed.

| Switch | LCD Message          | Test Operation  |
|--------|----------------------|---|
| 1      | Switch 01 is pressed | Toggle Relay1 (REL1)  |
| 2      | Switch 02 is pressed | Toggle Relay2 (REL2)  |
| 3      | Switch 03 is pressed | Toggle Red1 LED (RED1)  |
| 4      | Switch 04 is pressed | Toggle Red2 LED (RED2)  |
| 5      | Switch 05 is pressed | Toggle Green LED (GRN)  |
| 6      | Switch 06 is pressed | Toggle Blue LED (BLU)   |
| 7      | Switch 07 is pressed | Toggle Yellow LED (YLW)   |
| 8      | 7-Seg Testing        | Each 7 segment display digit counts from 0 to 9 then apply auto reset |
| 9      | Analog Testing       | LCD displays the analog voltage measured on port pin (PA0)            |
| 10     | Serial Testing       | The received text via the serial port is shown on LCD (115200bps)     |
| 11     | Switch 11 is pressed | ---   |
| 12     | Switch 12 is pressed | ---   |
| 13     | Switch 13 is pressed | ---   |
| 14     | Switch 14 is pressed | ---   |
| 15     | Switch 15 is pressed | ---   |
| 16     | Switch 16 is pressed | ---   |

We developed some example projects under the STM32 environment to test **Panda** kit sections separately. It is a good choice to download them from this link

<https://fares-pcb.com/product/arm-development-kit-panda/>

open example projects using STM32CubeIDE and upload to test

For our full range of products, see our website at <http://www.fares-pcb.com>  
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